



A Unified Approach to Differentially Private Bayes Point Estimation

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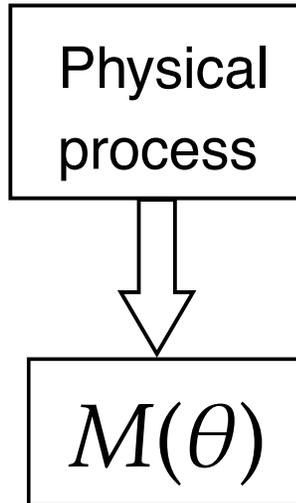


Motivation and Background

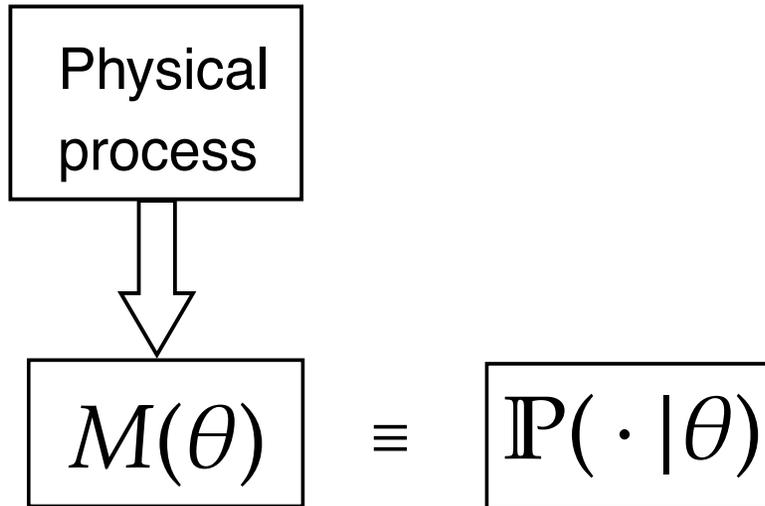


I. Point Estimate

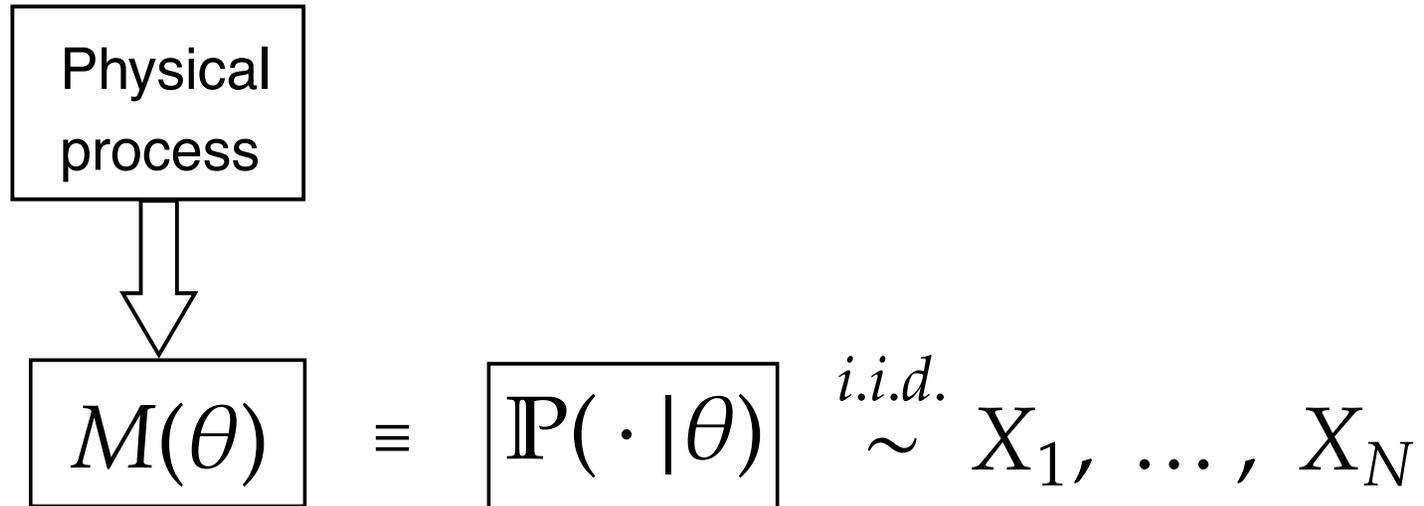
Point Estimate



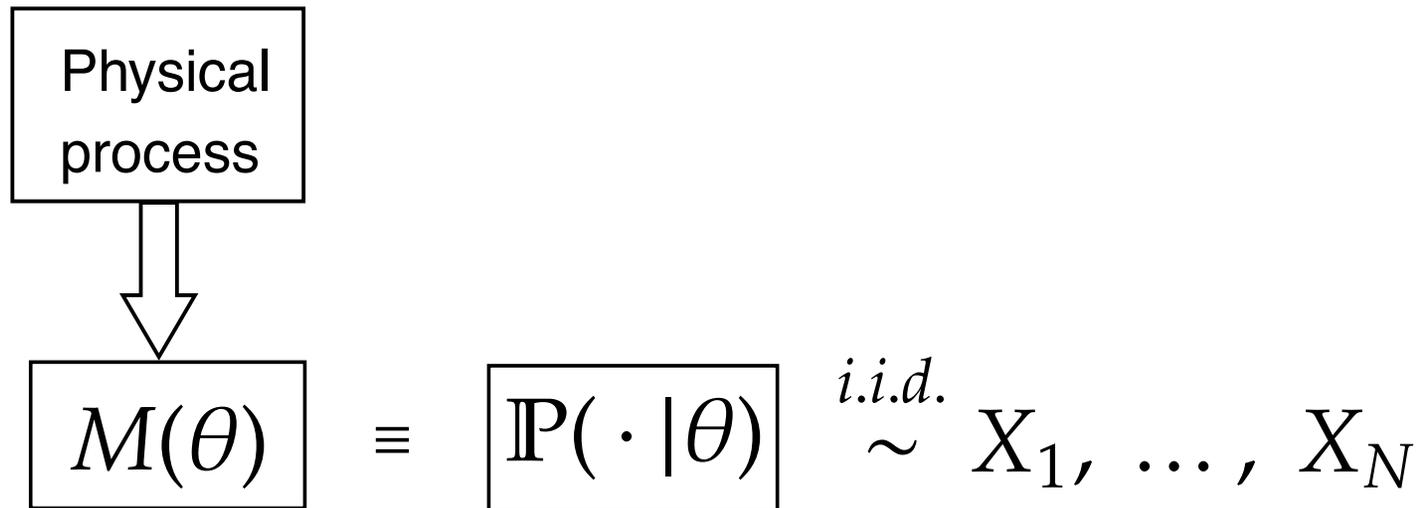
Point Estimate



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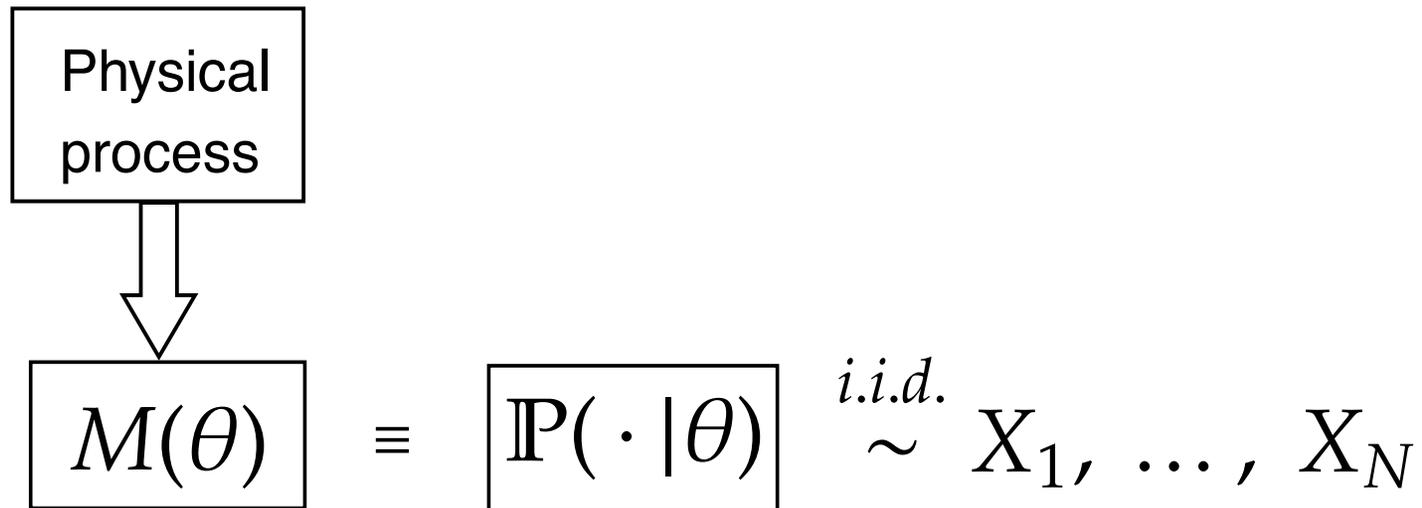


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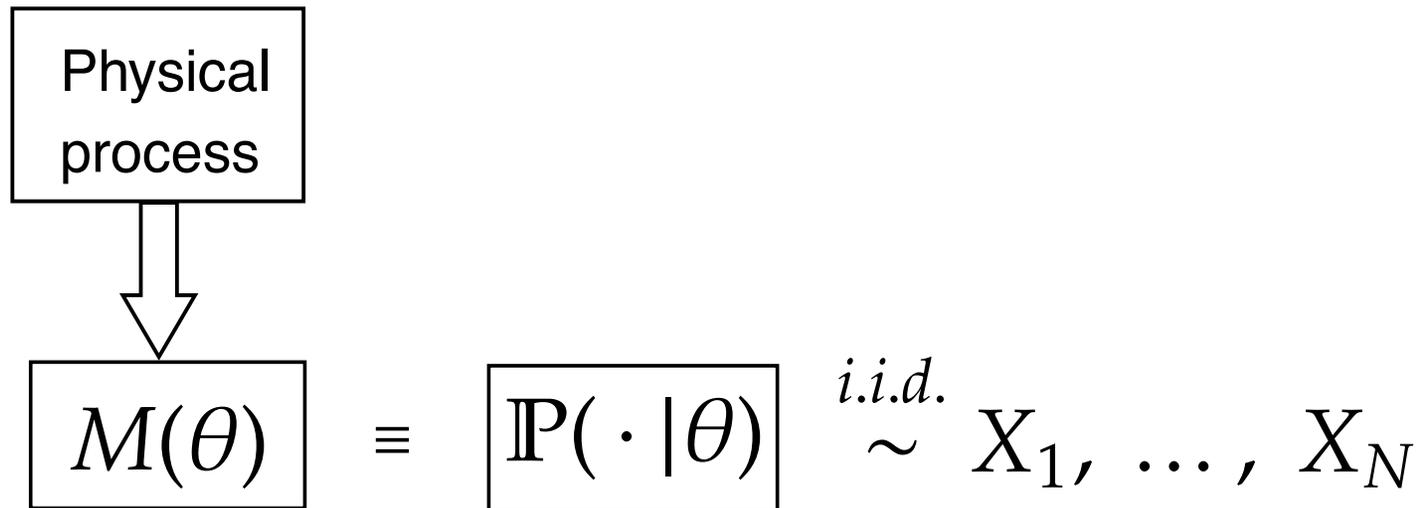
- ▶ Goal: Estimate unknown θ by observing $X = (X_1, \dots, X_N)$

Point Estimate



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Point Estimate

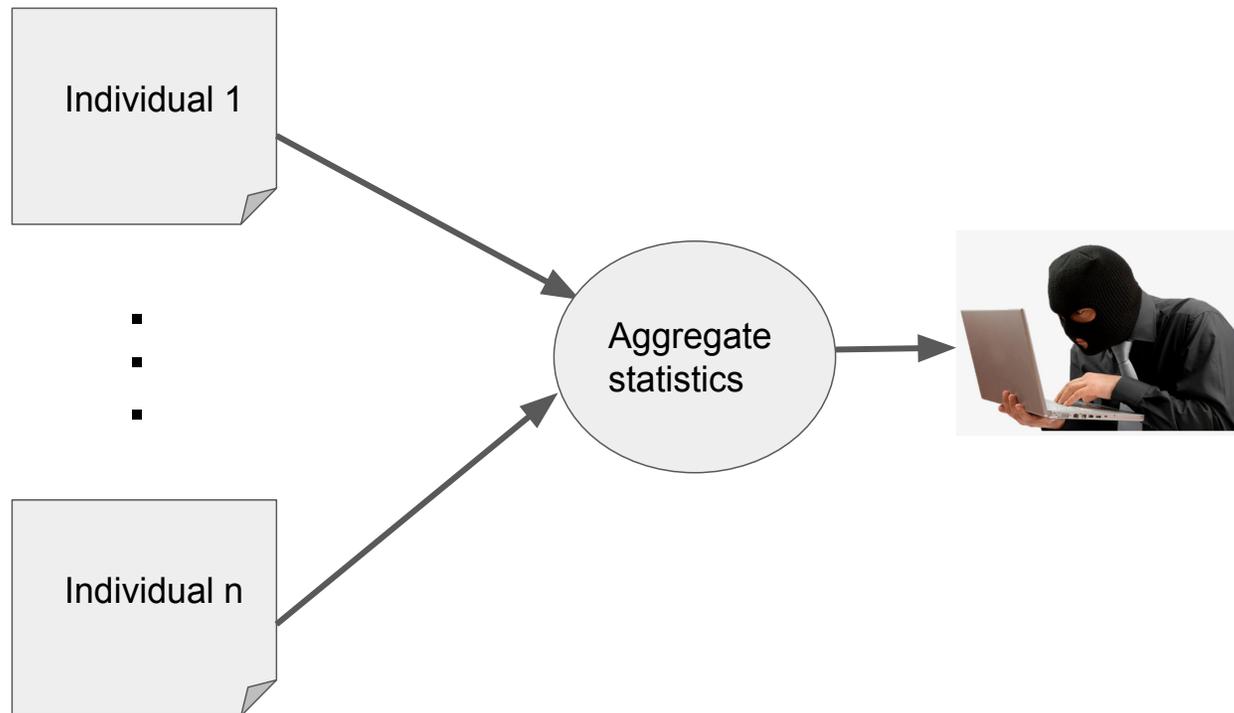


- ▶ Goal: Estimate unknown θ by observing $X = (X_1, \dots, X_N)$
- ▶ Point estimate: $\hat{\theta} := \hat{\theta}(X)$ Single quantity that is a possible value of θ
- ▶ Examples:

- ▶ $\text{Ber}(\theta)$: $\hat{\theta} = \frac{1}{N} \sum_{i=1}^N X_i$

- ▶ $\mathcal{N}(\mu, \sigma^2)$: $\hat{\sigma}^2 = \frac{1}{N-1} \sum_{i=1}^N (X_i - \mu)^2$

Need for Privacy in Point Estimates

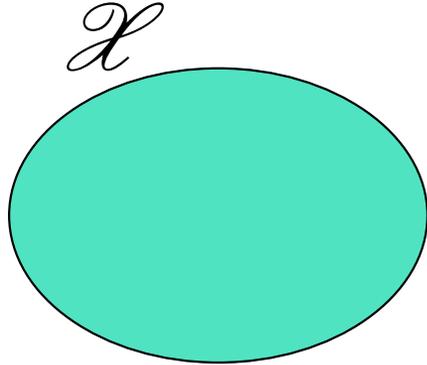


- ▶ Aggregate statistics: Sample mean, sample covariance,...
- ▶ Possible to infer an individual¹

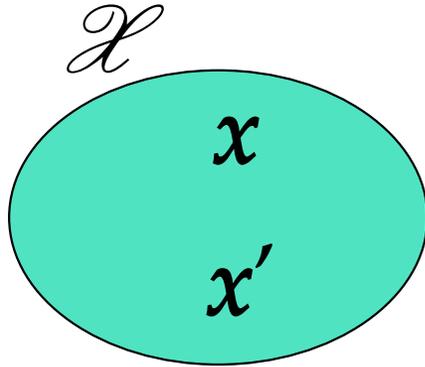
¹Homer, N. et al. "Resolving individuals contributing trace amounts of DNA to highly complex mixtures using high-density SNP genotyping microarrays". PLOS Genetics, 2008.

II. Differential Privacy

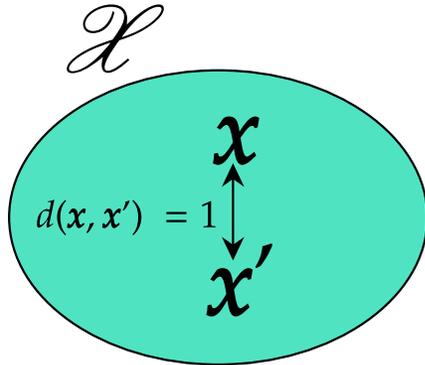
Differential Privacy (DP)



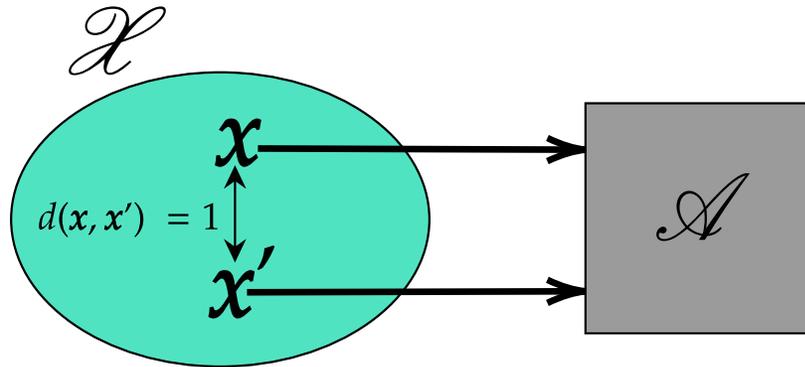
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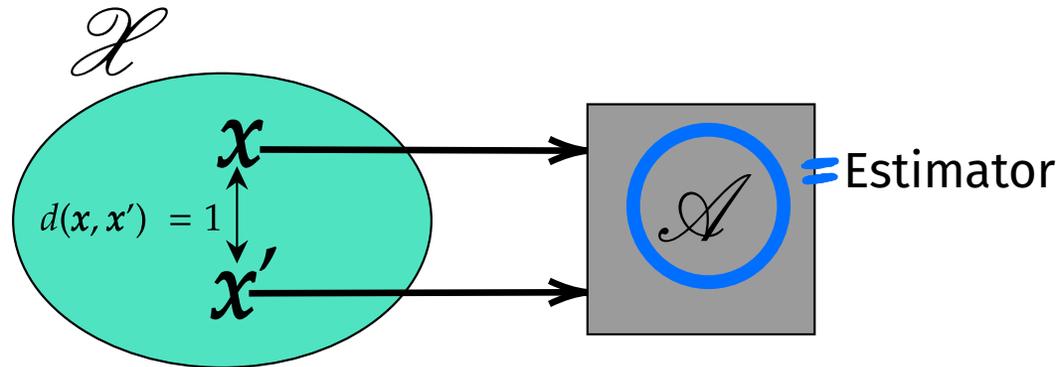
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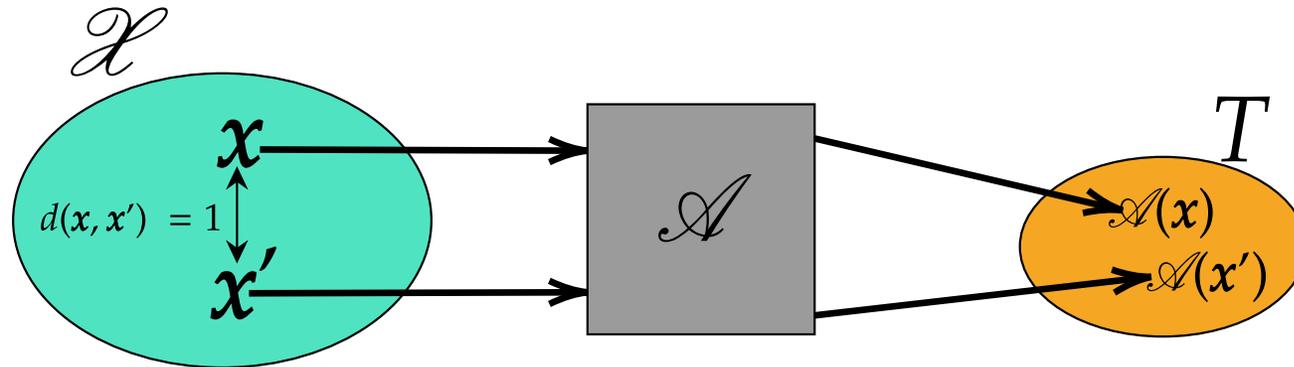
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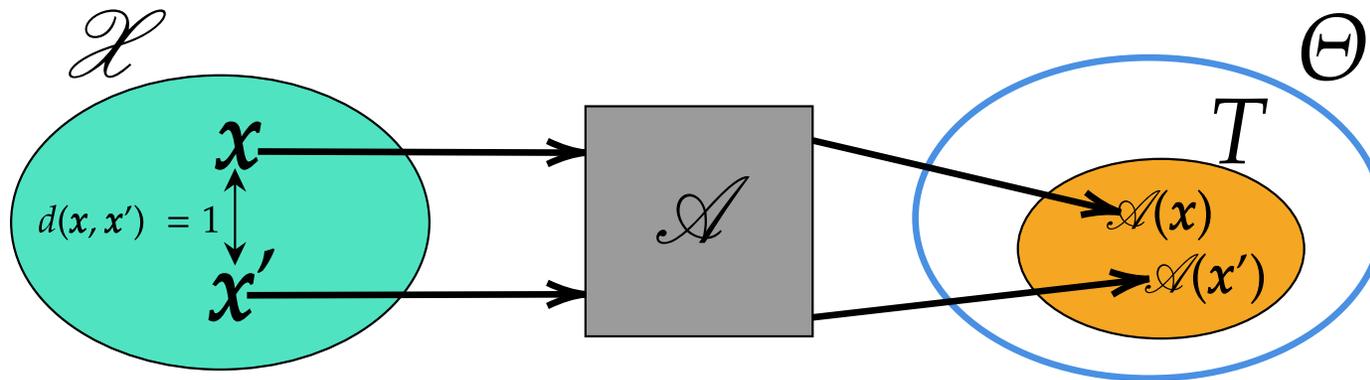
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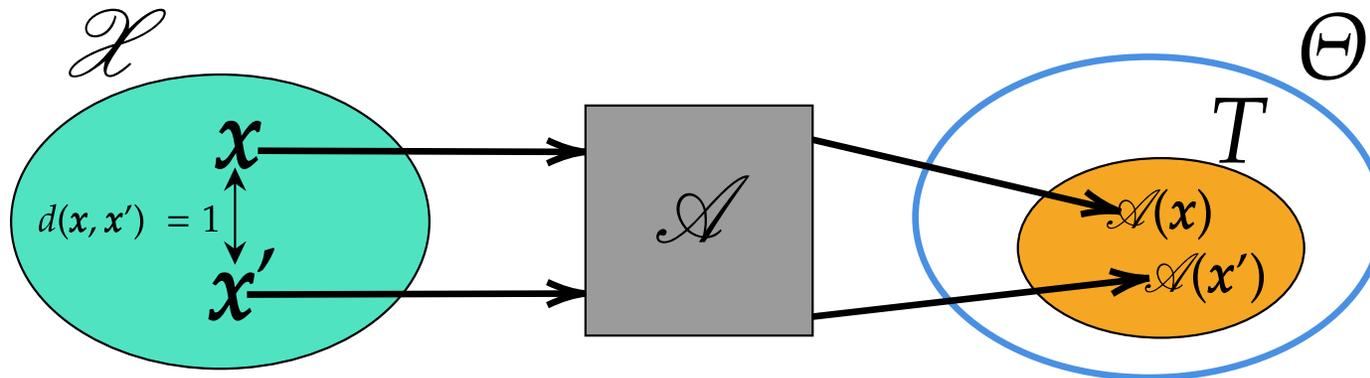
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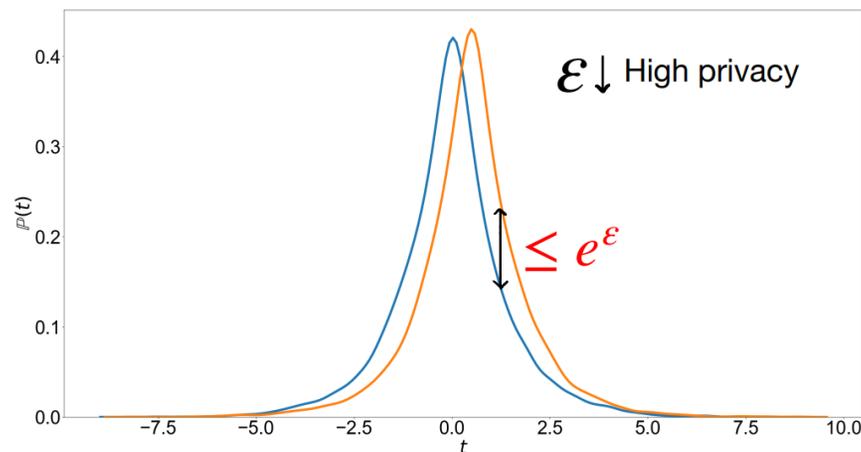
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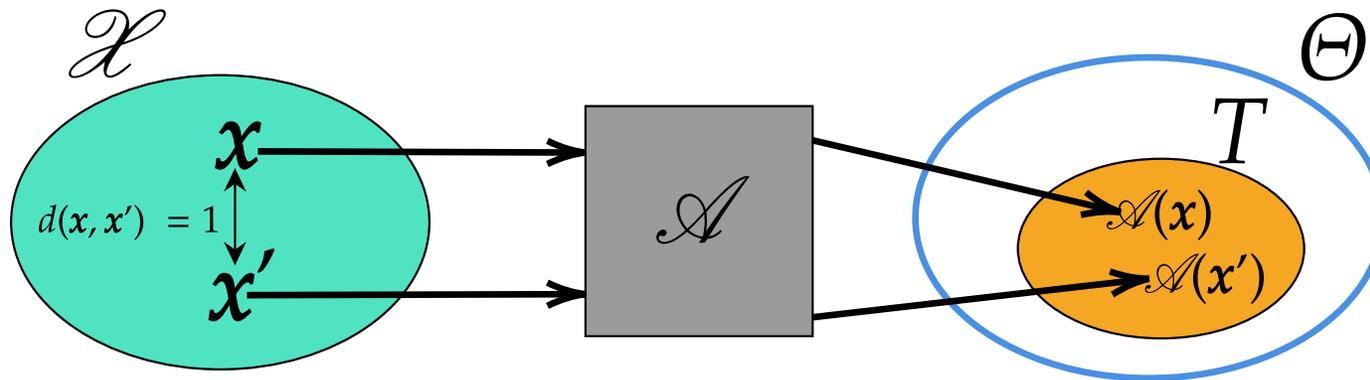


DP definition²: $\Pr[\mathcal{A}(\mathbf{x}) \in T] \leq e^\epsilon \Pr[\mathcal{A}(\mathbf{x}') \in T]$

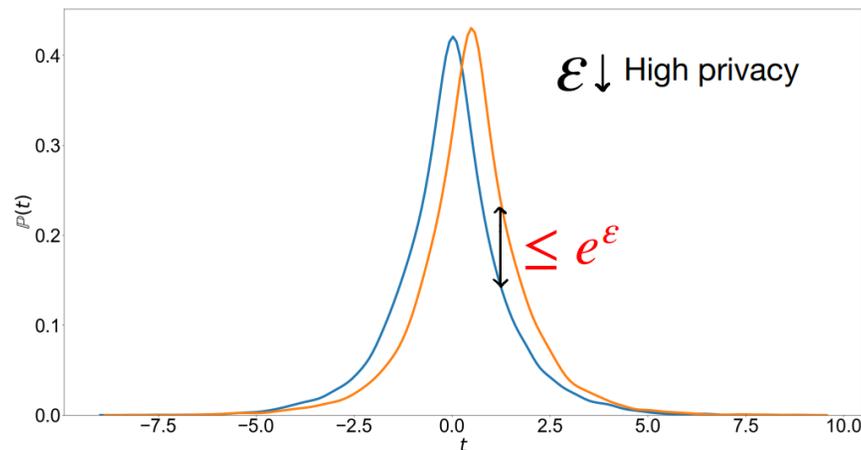


²C. Dwork and A. Roth. “The Algorithmic Foundations of Differential Privacy”. Foundations and Trends in Theoretical Computer Science. 2014

Differential Privacy (DP)

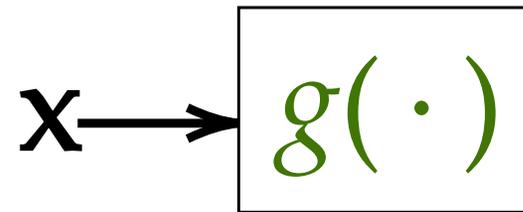


DP definition: $\Pr[\mathcal{A}(x) \in T] \leq e^\epsilon \Pr[\mathcal{A}(x') \in T]$



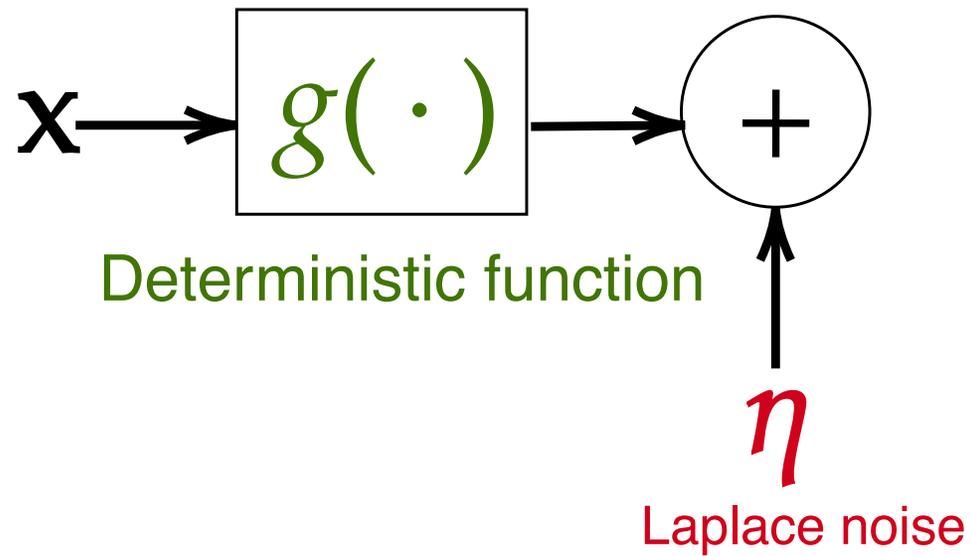
How to design \mathcal{A} ?

The Laplace Mechanism

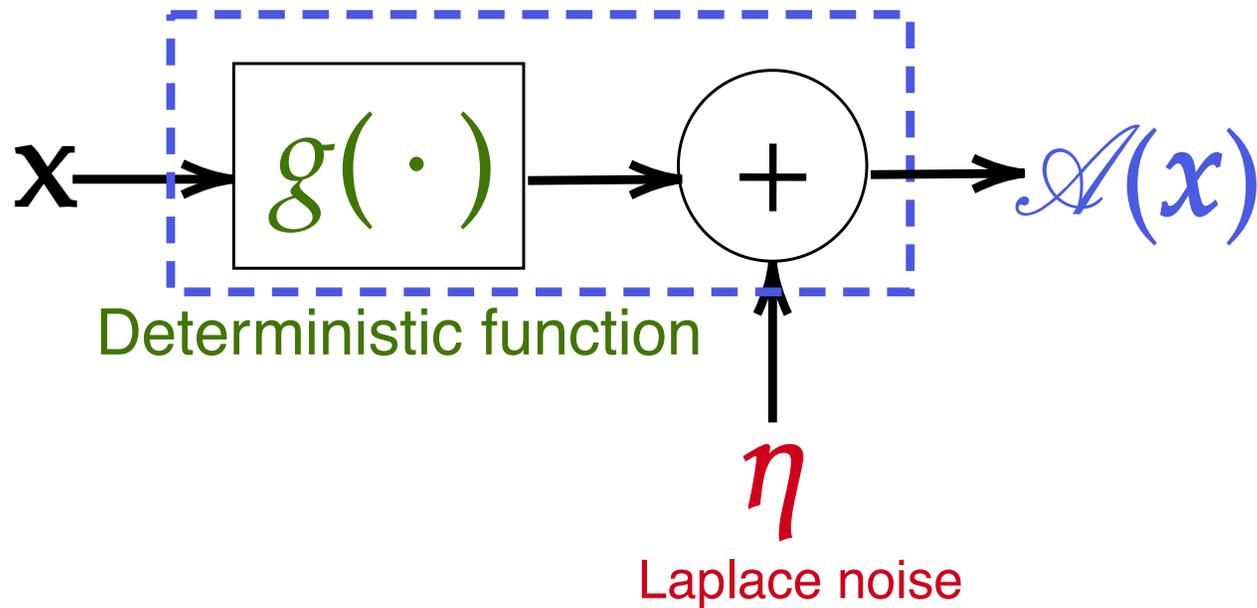


Deterministic function

The Laplace Mechanism

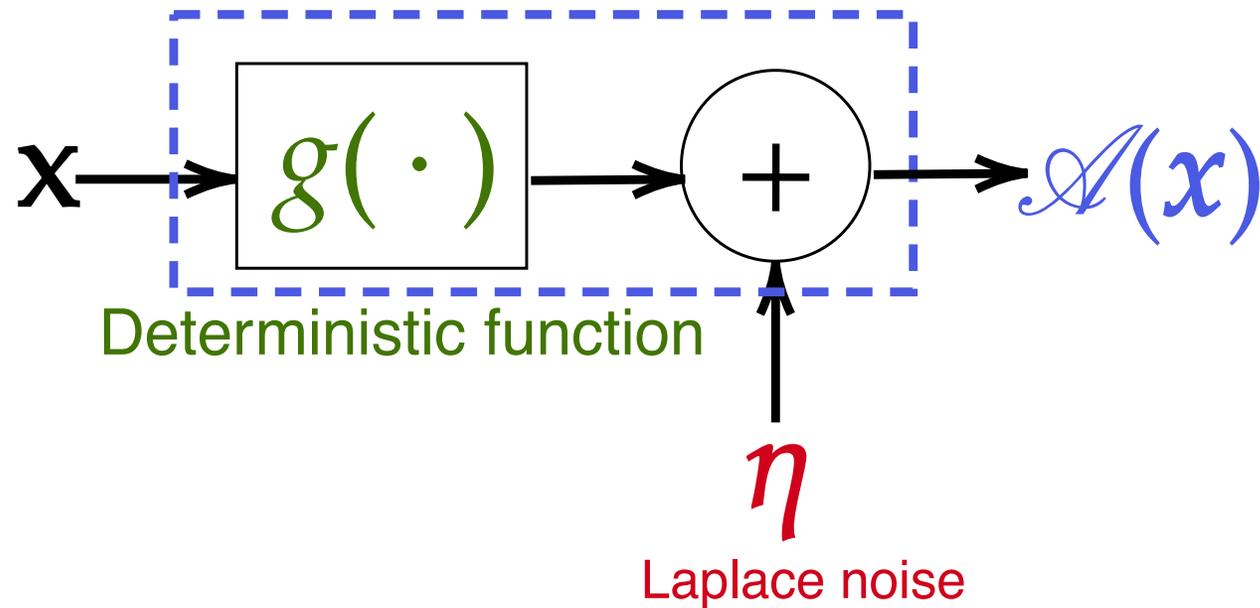


The Laplace Mechanism



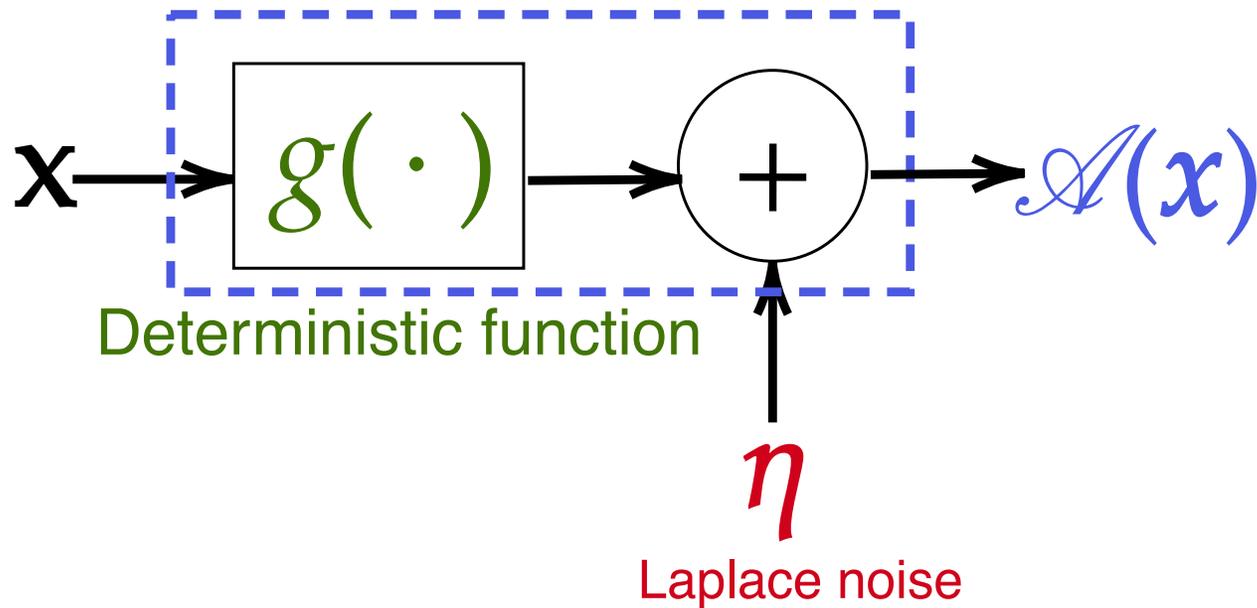
$$\eta_i \sim \text{Lap}\left(0, \frac{\sigma_g}{\epsilon}\right)$$

The Laplace Mechanism



$$\eta_i \sim \text{Lap}(0, \frac{\sigma_g}{\epsilon}) = ?$$

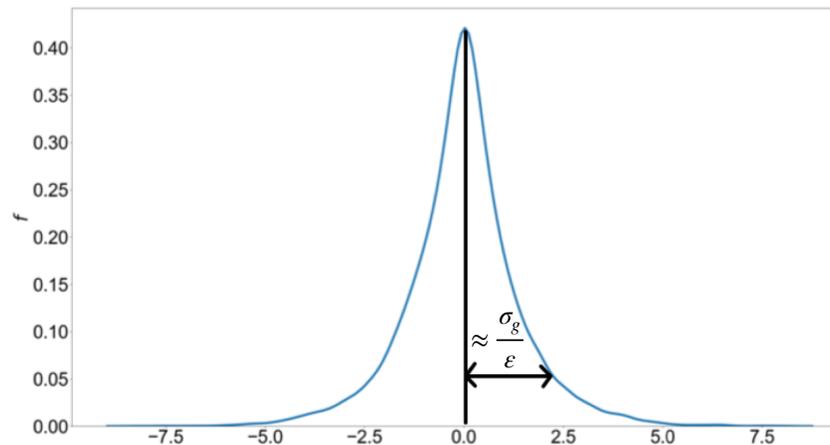
The Laplace Mechanism



$$\eta_i \sim \text{Lap}\left(0, \frac{\sigma_g}{\epsilon}\right)$$

$$\sigma_g = \sup_{\mathbf{x}, \mathbf{x}' \in \mathcal{X}: d(\mathbf{x}, \mathbf{x}')=1} \|g(\mathbf{x}) - g(\mathbf{x}')\|_1 \quad l_1 \text{ sensitivity}$$

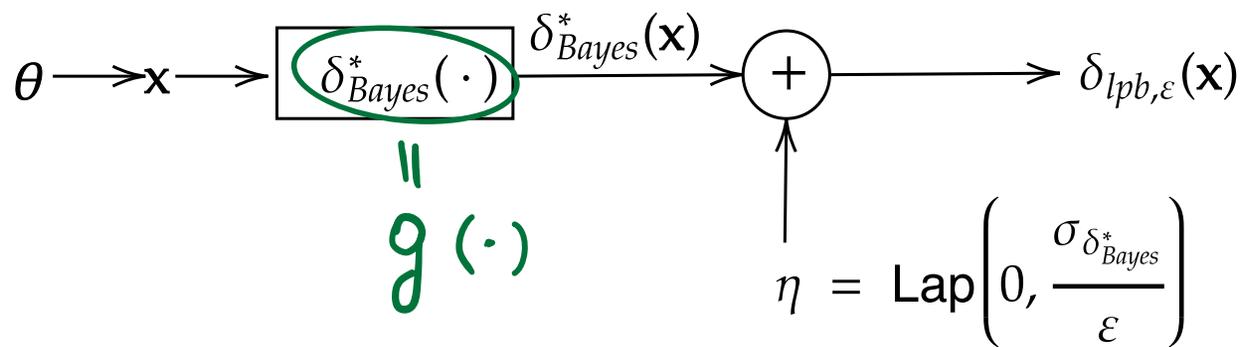
The Laplace Mechanism



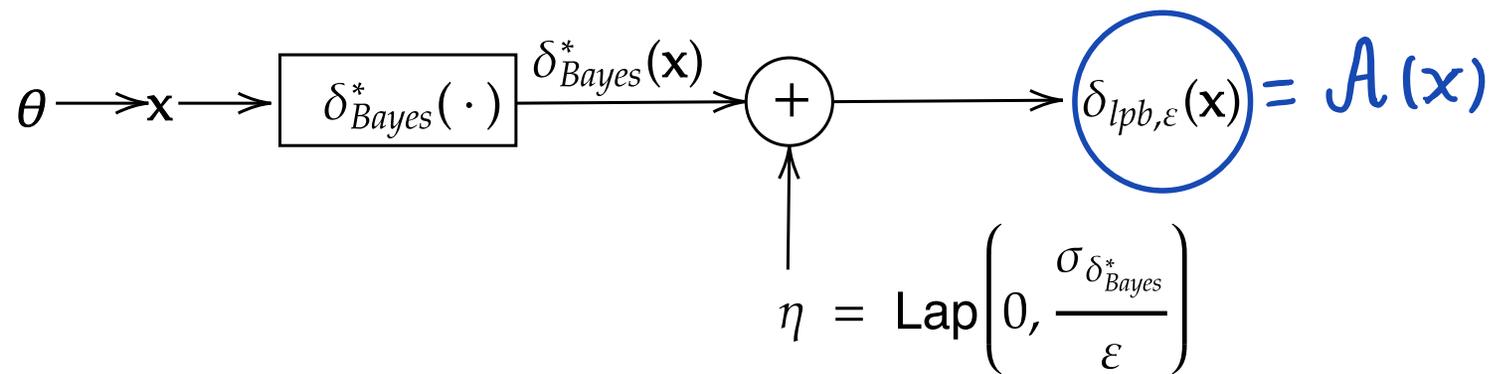
- ▶ Laplace mechanism enforces DP³
- ▶ DP via Laplace mechanism encounters accuracy-privacy trade off

³C. Dwork and A. Roth. “The Algorithmic Foundations of Differential Privacy”. Foundations and Trends in Theoretical Computer Science. 2014

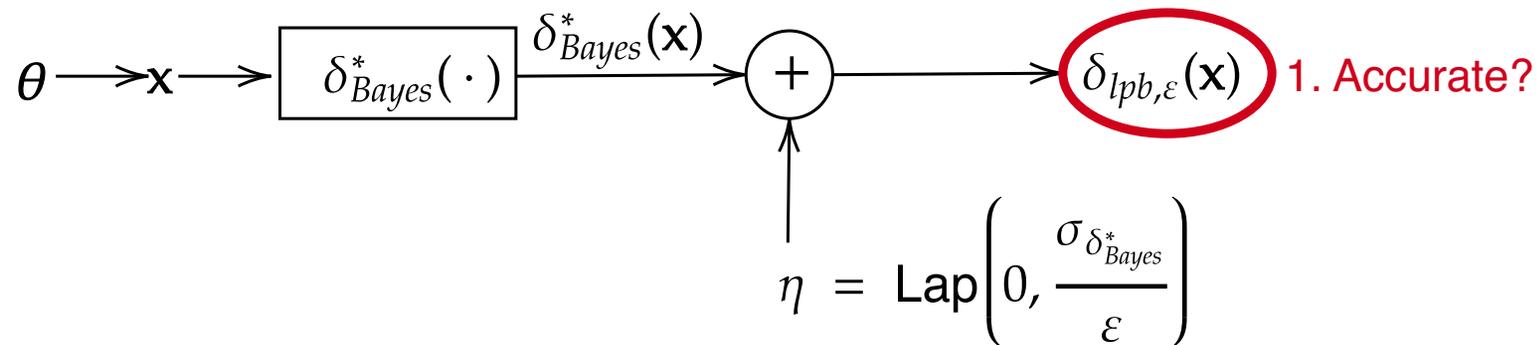
Bayes Point Estimate + Differential Privacy



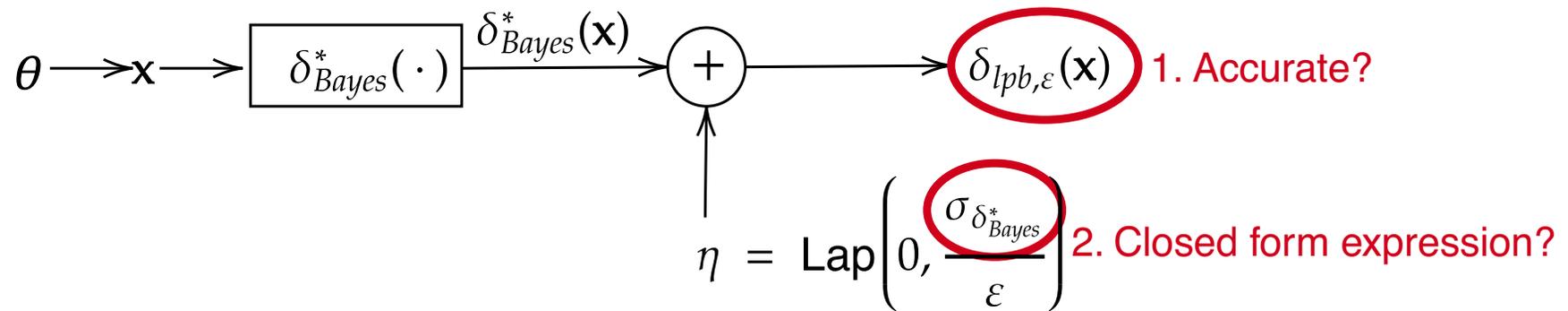
Bayes Point Estimate + Differential Privacy



Bayes Point Estimate + Differential Privacy



Bayes Point Estimate + Differential Privacy





Outline

Unified Approach (UBaPP Estimator)

UBaPP Estimator for Finite Case

Numerical Example

Conclusion



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Unified Approach (UBaPP Estimator)

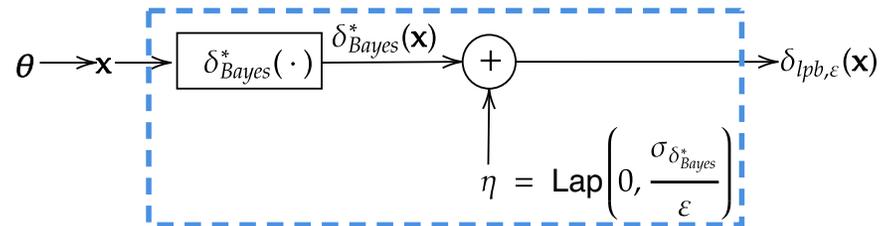
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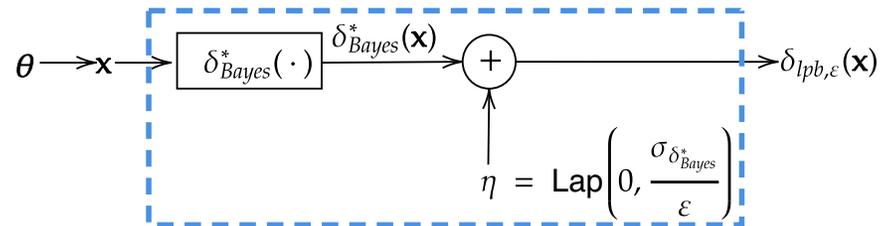
Unified Approach (UBaPP Estimator)

Earlier,

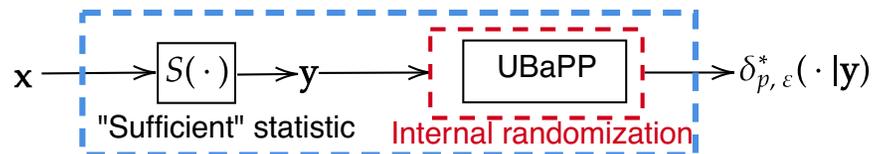


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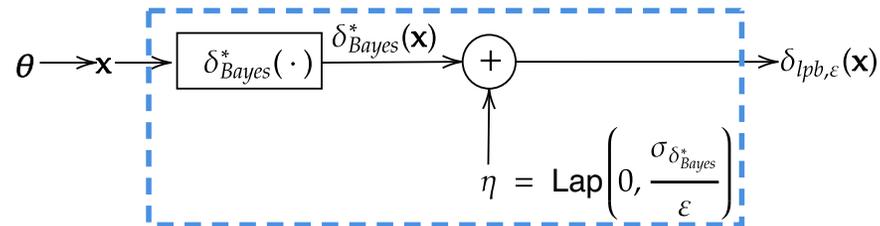


Instead, we propose

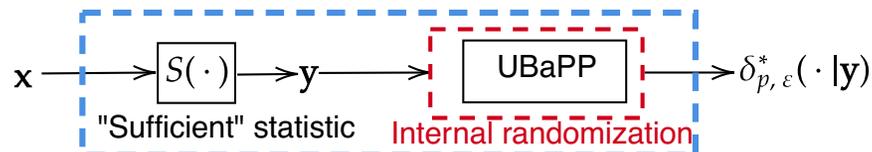


Unified Approach (UBaPP Estimator)

Earlier,



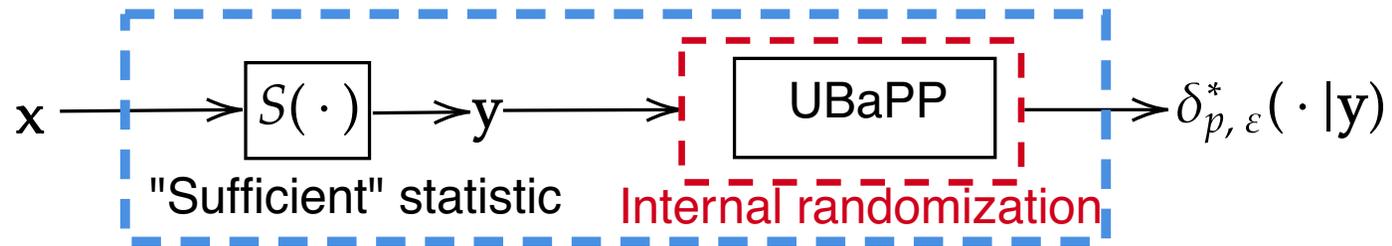
Instead, we propose



Randomized estimator (our approach)

DP is enforced by randomizing the estimator directly

Unified Approach (UBaPP Estimator)

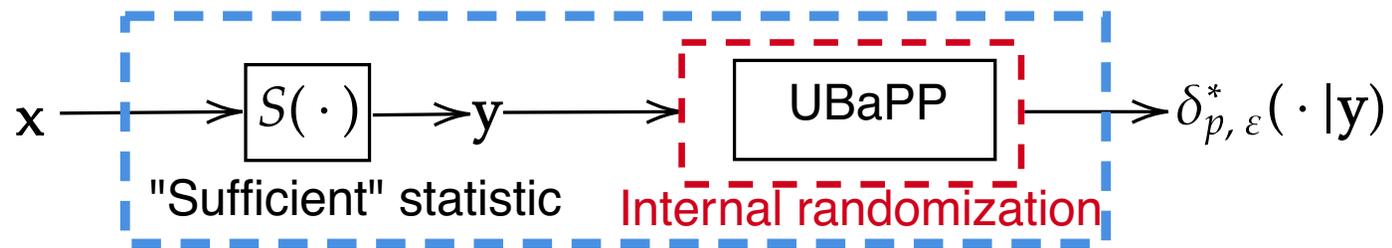


Non-private Bayes risk minimization:

Minimize risk

$$R(\delta, \pi) = \int_{\theta \in \Theta} \int_{\mathbf{y} \in \mathcal{Y}} L(\theta, \delta) q_{\theta}(\mathbf{y}) \pi(\theta) d\theta d\mathbf{y}$$

Unified Approach (UBaPP Estimator)



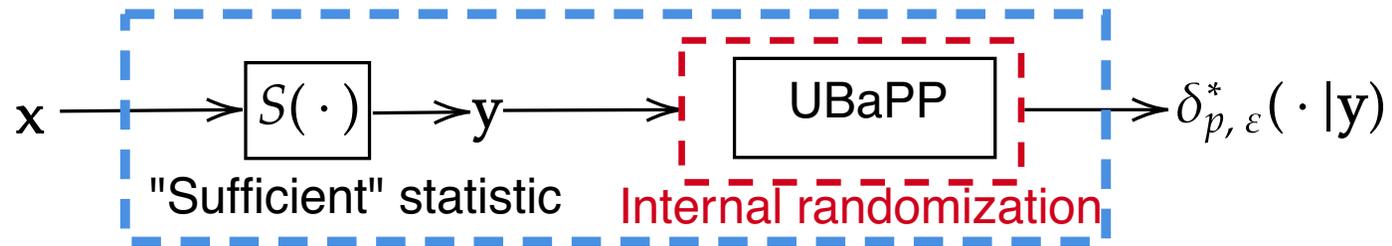
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Solution: Deterministic estimate!

Unified Approach (UBaPP Estimator)



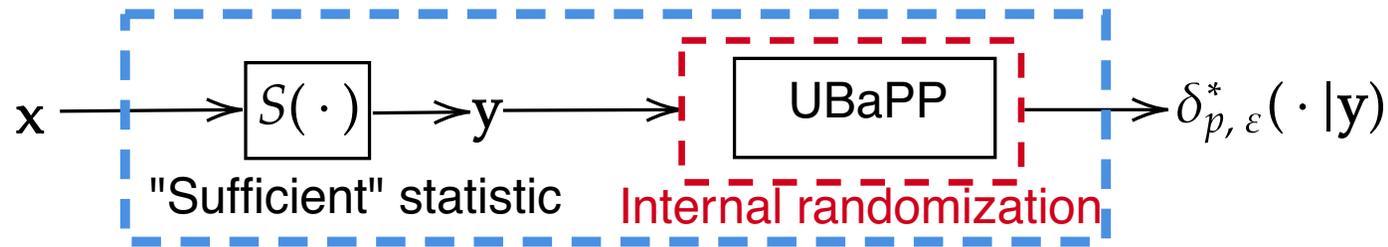
Private-Bayes risk minimization:

Minimize randomized risk

$$R(\delta_{p, \epsilon}, \pi) = \int_{\theta \in \Theta} \int_{\mathbf{y} \in \mathcal{Y}} \int_{\tilde{\theta} \in \Theta} L(\theta, \tilde{\theta}) q_{\theta}(\mathbf{y}) \pi(\theta) d\theta d\mathbf{y} \delta_{p, \epsilon}(\tilde{\theta} | \mathbf{y}) d\tilde{\theta}$$

Solution: Randomized estimate

Unified Approach (UBaPP Estimator)



Private-Bayes risk minimization:

Minimize randomized risk

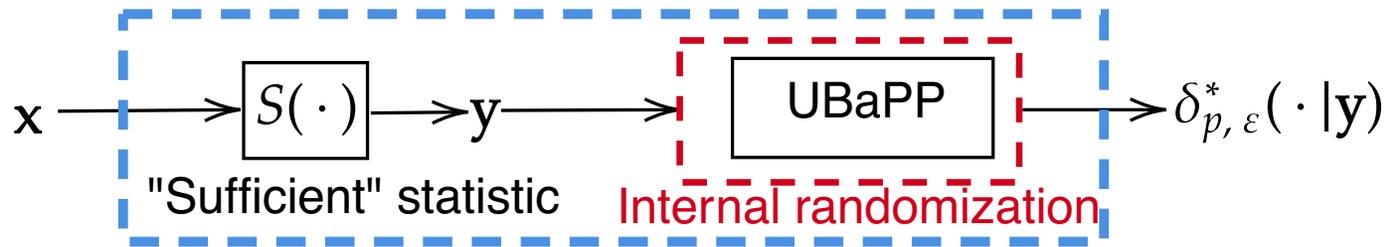
$$R(\delta_{p,\varepsilon}, \pi) = \int_{\theta \in \Theta} \int_{\mathbf{y} \in \mathcal{Y}} \int_{\tilde{\theta} \in \Theta} L(\theta, \tilde{\theta}) q_{\theta}(\mathbf{y}) \pi(\theta) d\theta d\mathbf{y} \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) d\tilde{\theta}$$

subject to

$$\delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}'), \text{ for each } \tilde{\theta} \in \Theta$$

DP constraint

Unified Approach (UBaPP Estimator)



Solution: UBaPP estimate

Private-Bayes risk minimization:

Minimize randomized risk

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Unified Approach (UBaPP Estimator)

UBaPP estimator is the solution to following convex program:

$$\begin{aligned}
 & \min_{\delta_{p,\varepsilon} \in \mathcal{P}(\mathcal{Y}, \Theta)} \int_{\Theta} \int_{\mathcal{Y}} \int_{\Theta} L(\theta, \tilde{\theta}) \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) q_{\theta}(\mathbf{y}) \pi(\theta) d\theta d\mathbf{y} d\tilde{\theta} \\
 & \text{s.t.} \quad \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x})) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x}')), \text{ for each } \tilde{\theta} \in \Theta \\
 & \quad \text{and } \mathbf{x}, \mathbf{x}' \in \mathcal{X} \text{ s.t. } d(\mathbf{x}, \mathbf{x}') = 1 \\
 & \quad \int_{\Theta} \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) d\mathbf{y} = 1, \text{ for each } \mathbf{y} \in \mathcal{Y} \\
 & \quad \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) \geq 0, \text{ for each } \mathbf{y} \in \mathcal{Y}, \tilde{\theta} \in \Theta
 \end{aligned}$$

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 & \text{s.t.} \quad \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x})) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x}')), \text{ for each } \tilde{\theta} \in \Theta \\
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s.t. $\delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x})) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x}'))$, for each $\tilde{\theta} \in \Theta$

DP constraint

and $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$ s.t. $d(\mathbf{x}, \mathbf{x}') = 1$

$$\int_{\Theta} \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) d\mathbf{y} = 1, \text{ for each } \mathbf{y} \in \mathcal{Y}$$

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s.t. $\delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x})) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x}'))$, for each $\tilde{\theta} \in \Theta$
and $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$ s.t. $d(\mathbf{x}, \mathbf{x}') = 1$

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Randomization constraint

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 \end{aligned}$$

UBaPP is optimal by construction!

Unified Approach (UBaPP Estimator)

UBaPP estimator is the solution to following convex program:

$$\begin{aligned}
 & \min_{\delta_{p,\varepsilon} \in \mathcal{P}(\mathcal{Y}, \Theta)} \int_{\Theta} \int_{\mathcal{Y}} \int_{\Theta} \|\theta - \tilde{\theta}\|^2 \delta_{p,\varepsilon}(\tilde{\theta} | \mathbf{y}) q_{\theta}(\mathbf{y}) \pi(\theta) d\theta d\mathbf{y} d\tilde{\theta} \\
 & \text{s.t.} \quad \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x})) \leq e^{\varepsilon} \delta_{p,\varepsilon}(\tilde{\theta} | S(\mathbf{x}')), \text{ for each } \tilde{\theta} \in \Theta \\
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UBaPP Estimator for Finite Case

UBaPP estimator \equiv solution to a linear program:

$$\begin{aligned} \min_{\mathbf{P} \in \mathbb{R}^{|\Theta| \times |\mathcal{Y}|}} \quad & \text{tr}(\mathbf{Q} \text{diag}(\boldsymbol{\pi}) \mathbf{L} \mathbf{P}) \\ \text{s.t.} \quad & \mathbf{P}_{k,i} \leq e^\varepsilon \mathbf{P}_{k,i'}, \text{ for all } k \in \{1, \dots, |\Theta|\} \\ & \text{and } i, i' \in \{1, \dots, |\mathcal{Y}|\} \text{ s.t. } d(\mathbf{x}_i, \mathbf{x}_{i'}) = 1 \\ & \mathbf{1}^T \mathbf{P} = \mathbf{1}^T \\ & \mathbf{P} \geq 0 \end{aligned}$$

UBaPP Estimator for Finite Case

UBaPP estimator \equiv solution to a linear program:

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Solved using CVXPY!



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Numerical Example

Private estimation of Bernoulli parameter (θ) using K trials

► $\Theta = [0, 1]$



Numerical Example

Private estimation of Bernoulli parameter (θ) using K trials

$$\blacktriangleright \Theta = [0, 1] \xrightarrow{\text{discretize}} \theta_j \stackrel{i.i.d.}{\sim} \pi, j \in \{1, \dots, M\}$$

Numerical Example

Private estimation of Bernoulli parameter (θ) using K trials

▶ $\Theta = [0, 1] \xrightarrow{\text{discretize}} \theta_j \stackrel{i.i.d.}{\sim} \pi, j \in \{1, \dots, M\}$

▶ $\mathcal{Y} = \{0, \dots, K\}$

Numerical Example

Private estimation of Bernoulli parameter (θ) using K trials

▶ $\Theta = [0, 1] \xrightarrow{\text{discretize}} \theta_j \stackrel{i.i.d.}{\sim} \pi, j \in \{1, \dots, M\}$

▶ $\mathcal{Y} = \{0, \dots, K\}$

▶ $S(\mathbf{x}) = \sum_{i=1}^K x_i \quad x_i \stackrel{i.i.d.}{\sim} \text{Ber}(\theta_j), i = 1, \dots, K$

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Laplace Bayes Private Point (LBaPP) estimator for this setup:

$$\delta_{lpb, \varepsilon} = \frac{1}{K+2} \left(\sum_{i=1}^K x_i + 1 \right) + \text{Lap} \left(0, \frac{1}{(K+2)\varepsilon} \right)$$

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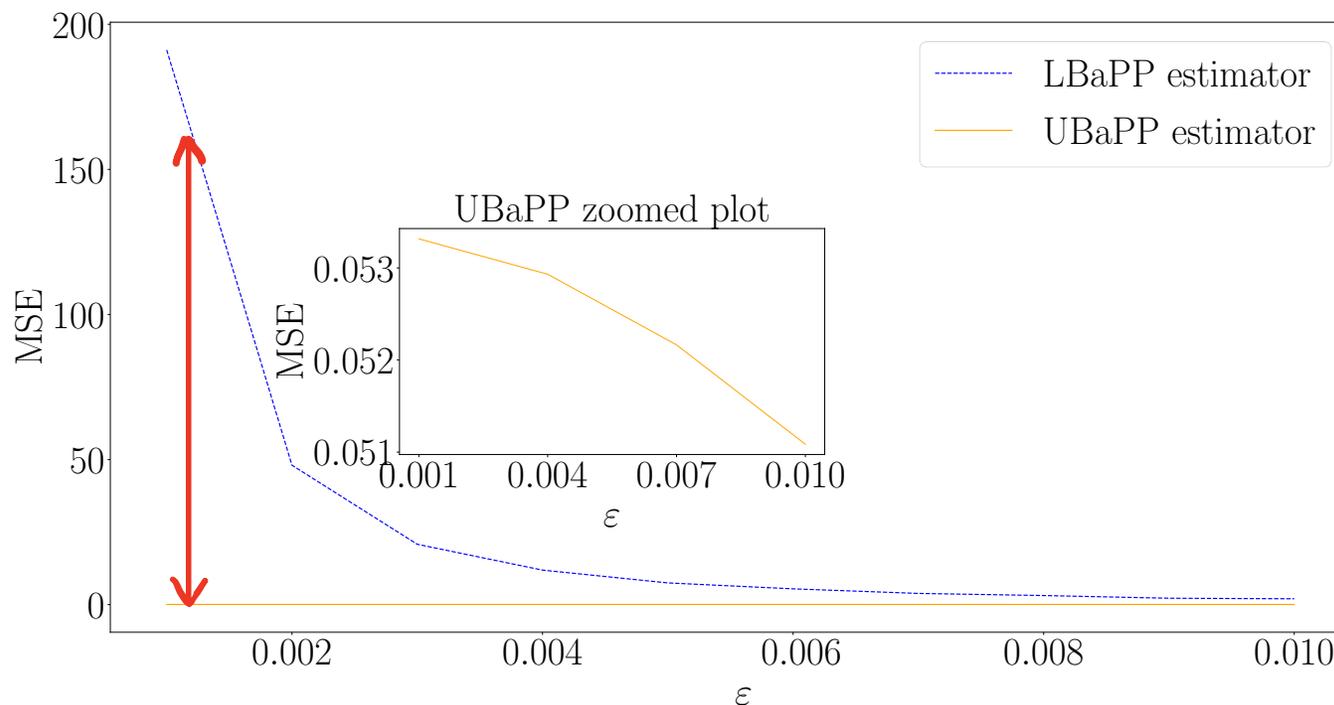
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Plots (MSE v.s. ϵ)

For a fixed K ($K = 100$)

High privacy regime

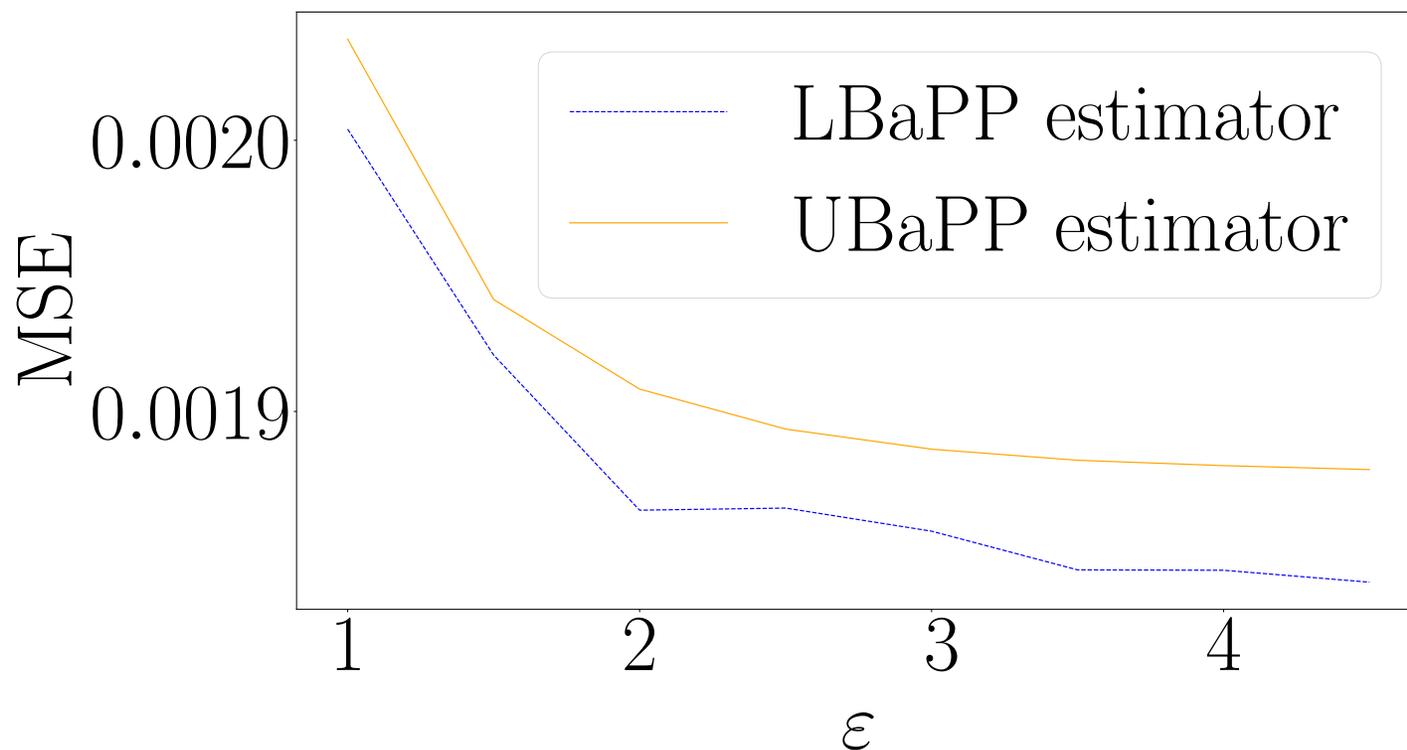


High accuracy is achieved by our approach!

Plots (MSE v.s. ϵ)

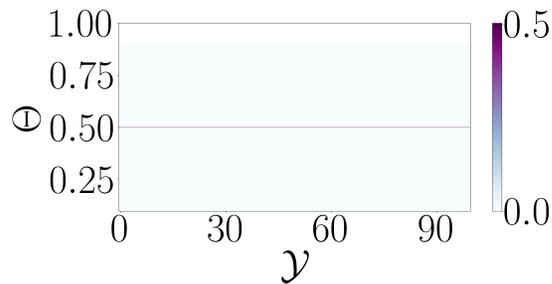
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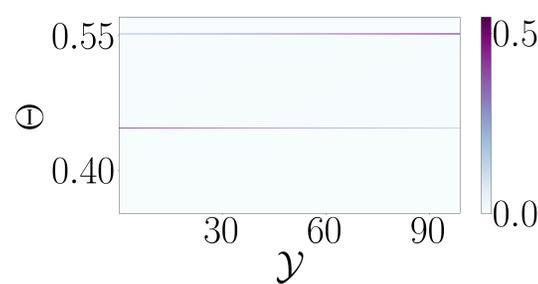


Comparable performance!

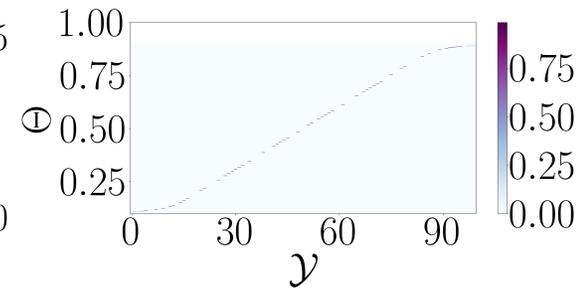
Heat Maps



$\varepsilon = 10^{-4}$



$\varepsilon = 10^{-1}$



$\varepsilon = 5$



- ▶ $\varepsilon = 10^{-4}$: Deterministic estimate, independent of \mathbf{y} , no inference about \mathbf{x}
- ▶ $\varepsilon = 10^{-1}$: Randomized estimate, still independent of \mathbf{y} , still no inference about \mathbf{x}
- ▶ $\varepsilon = 5$: Deterministic estimate, strongly dependent on \mathbf{y} , complete inference about \mathbf{x}



Outline

Unified Approach (UBaPP Estimator)

UBaPP Estimator for Finite Case

Numerical Example

Conclusion



Conclusion

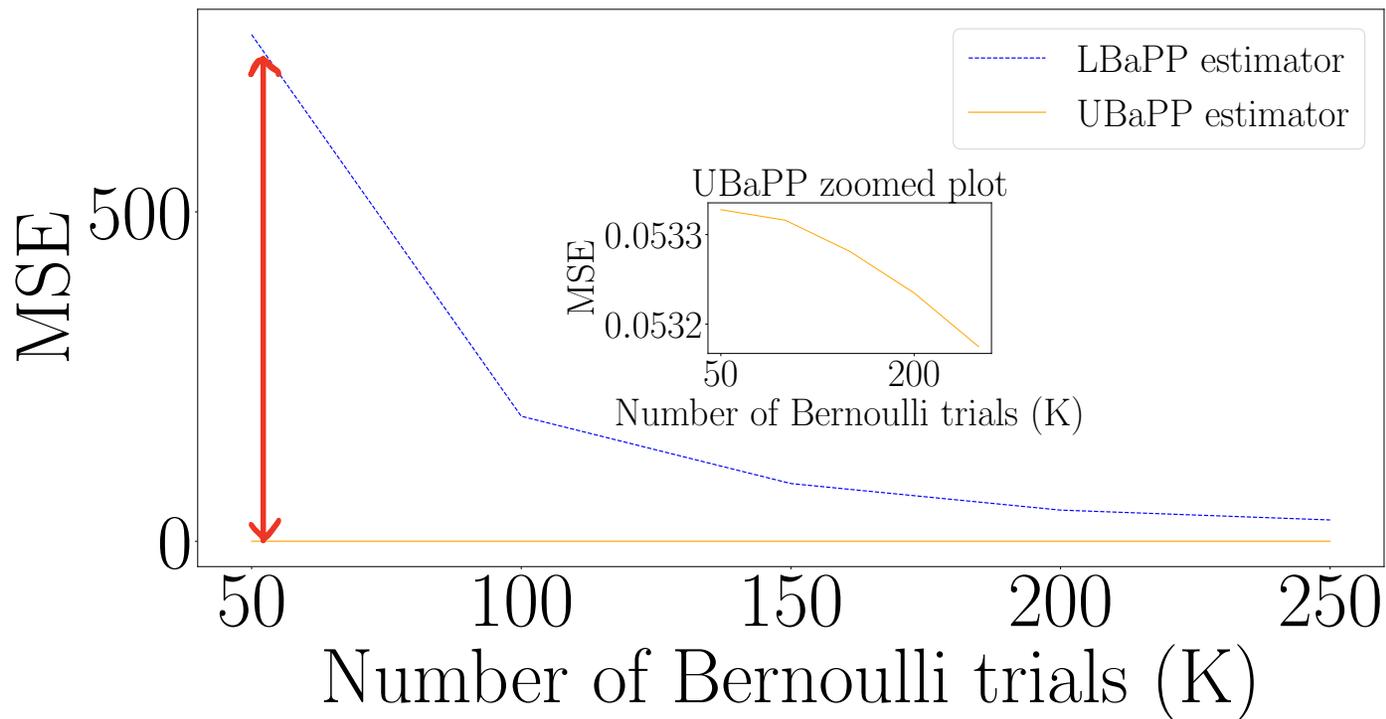
- ▶ Provided a unified approach to yield Bayes point estimate subject to differential privacy
- ▶ The “noise” is implicitly “added” by randomizing the estimator directly
- ▶ Demonstrated promising result in the limiting case (high-privacy regime) for the finite case via a numerical example
- ▶ Future work: Analyze the UBaPP estimator for high dimensional parameter and observation space



Thank You

Plots (MSE v.s. K)

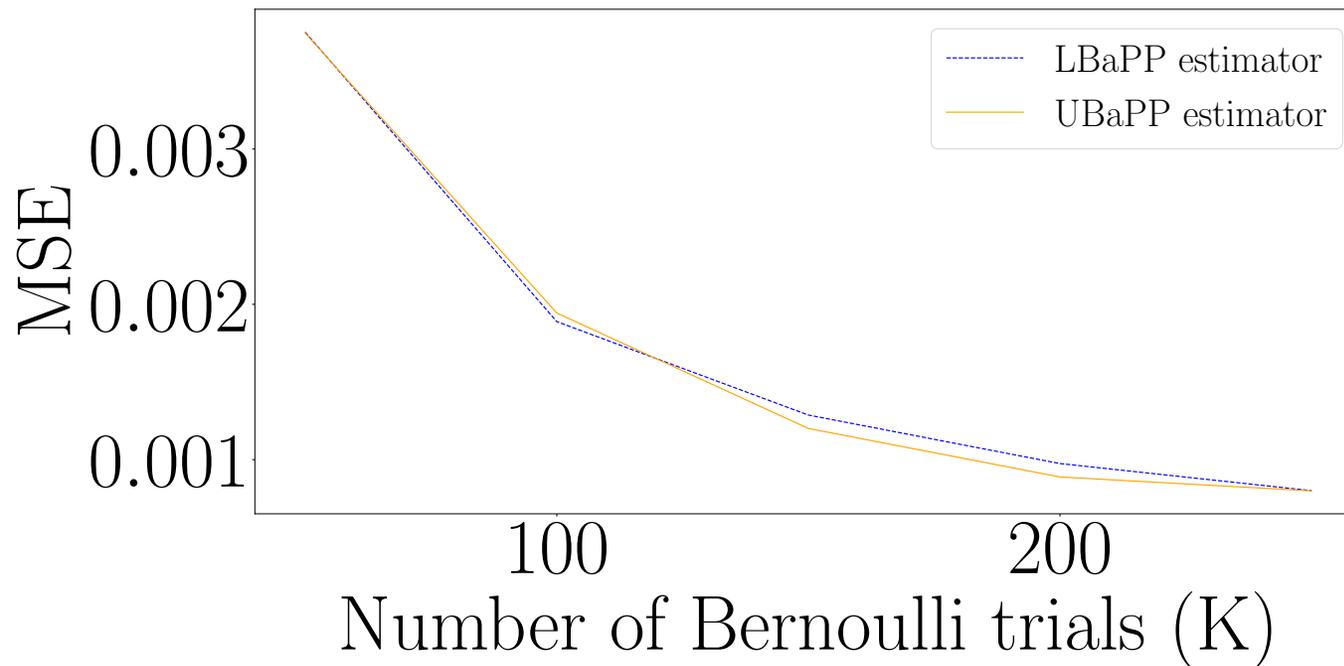
High privacy regime ($\epsilon = 10^{-3}$)



High gain in sample complexity!

Plots (MSE v.s. K)

Low privacy regime ($\epsilon = 5$)



Comparable sample complexity!